Discrete Fourier Transforms

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Fourier Transform

In this lecture, we will discuss:

- The Fourier transform,
- The discrete Fourier transform
- The fast Fourier transform
- Examples using the FFTW library



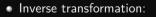


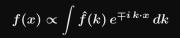
Fourier Transform recap

• Let f be a function of some spatial variable x.

• Transform to a function \hat{f} of the angular wavenumber k:

$$\hat{f}(k) \propto \int f(x) \, e^{\pm i \, k \cdot x} \, dx$$







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$$f(x) = e^{-|x|}$$

Fourier Transform

- Fourier made the claim that any function can be expressed as a harmonic series.
- The FT is a mathematical expression of that.
- Constitutes a linear basis transformation in function space.
- Transforms from spatial to wavenumber, or time to frequency, etc.
- Constants and signs are just convention.*
 - * some restritions apply.



Discrete Fourier Transform



C. F. Gauss

 Given a set of n function values on a regular grid:

 $x_j = j\Delta x; \quad f_j = f(j\Delta x)$

ullet Transform to n other values

$$\hat{f}_q = \sum_{j=0}^{n-1} f_j \, e^{\pm \, 2\pi i \, j \, q/n}$$

• Easily back-transformed:

$$f_j = rac{1}{n} \sum_{q=0}^{n-1} \hat{f}_q \, e^{\mp \, 2\pi i \, j \, q/n}$$

• Solution is periodic: $\hat{f}_{-q} = \hat{f}_{n-q}$. You run the risk of aliasing, as q is equivalent to $q + \ell n$. Cannot resolve frequencies higher than q = n/2 (Nyquist).

Slow Fourier Transform

$$\hat{f}_q = \sum_{j=0}^{n-1} f_j \, e^{\pm \, 2\pi i \, j \, q/n}$$

- Discrete fourier transform is a linear transformation.
- In particular, it's a matrix-vector multiplication.
- Naively, costs $\mathcal{O}(n^2)$. Slow!



Slow DFT

#include <complex>
#include <rarray>
#include <cmath>

```
using complex = std::complex<double>;
void fft slow(rvector<complex>& f, rvector<complex>& fhat, bool inverse)
    const int n = fhat.size():
    const int sign = inverse*(-1) + (1-inverse)*(+1);
    const double v = sign*2*M_PI/n;
    for (int q = 0; q < n; q++)
        fhat[a] = 0.0:
        for (int m = 0; m < n; m++) {
            fhat[g] += complex(cos(v*g*m), sin(v*g*m)) * f[m];
```

Note that the inverse leaves out the 1/n normalization; this is common in many implementations. Even Gauss realized $O(n^2)$ was too slow and came up with ...

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Fast Fourier Transform

- Derived in partial form several times before and even after Gauss, because he'd just written it in his diary in 1805 (published later).
- Rediscovered (in general form) by Cooley and Tukey in 1965.

Basic idea

- Write each *n*-point FT as a sum of two $\frac{n}{2}$ point FTs.
- Do this recursively $2 \log n$ times.
- Each level requires $\sim n$ computations: $\mathcal{O}(n\log n)$ instead of $\mathcal{O}(n^2)$.
- Could as easily divide into 3, 5, 7, ... parts.

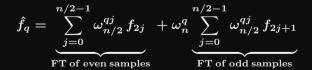


Fast Fourier Transform: How is it done?

- Define $\omega_n = e^{2\pi i/n}$.
- Note that $\omega_n^2 = \omega_{n/2}$.
- DFT takes form of matrix-vector multiplication:

$$\widehat{f}_q = \sum_{j=0}^{n-1} \, \omega_n^{qj} \, f_j$$

• With a bit of rewriting (assuming *n* is even):



- Repeat, until the lowest level (for n=1, $\hat{f}=f$).
- Note that a fair amount of shuffling is involved.

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Inverse DFT

• Inverse DFT is similar to forward DFT, up to a normalization: almost just as fast.

$$f_j = rac{1}{n} \sum_{q=0}^{n-1} \hat{f}_q \, e^{\mp \, 2 \pi i \, j \, q/n}$$

- FFT allows quick back-and-forth between space and wavenumber domain, or time and frequency domain.
- Allows parts of the computation and/or analysis to be done in the most convenient or efficient domain.



Fast Fourier Transform: Already done!

We've said it before and we'll say it again: Do not write your own: use existing libraries! Why?

- Because getting all the pieces right is tricky;
- Getting it to compute fast requires intimate knowledge of how processors work and access memory;
- Because there are libraries available.

Examples:

- ► FFTW3 (Faster Fourier Transform in the West, version 3)
- ► cuFFT
- ► Intel MKL
- ► IBM ESSL
- Because you have better things to do.



Example of using a library: FFTW

Version of previous (slow) FT that calls FFTW

```
#include <complex>
#include <rarray>
#include <fftw3.h>
using complex = std::complex<double>;
void fft_fast(rvector<complex>& f, rvector<complex>& fhat, bool inverse)
Ł
    const int n = f.size();
    const int sign = inverse*FFTW BACKWARD+(1-inverse)*FFTW FORWARD:
    fftw_plan p = fftw_plan_dft_1d(n,
                   reinterpret cast<fftw complex*>(f.data()).
                   reinterpret cast<fftw complex*>(fhat.data()).
                   sign.
                   FFTW_ESTIMATE);
    fftw execute(p):
    fftw destrov plan(p):
```



Notes

- Creates a plan first. This is a mandatory step for fftw.
- An fftw_plan contains all information necessary to compute the transform, including the pointers to the input and output arrays.
- FFTW uses its own complex number type, completely compatible with C++'s complex numbers, except C++ does not know that. So, casts.
- Plans can be reused in the program, and even saved on disk!
- When creating a plan, you can have FFTW measure the fastest way of computing dft's of that size (FFTW_MEASURE), instead of guessing (FFTW_ESTIMATE).
- FFTW works with doubles by default, but you can install single precision too.



Consider an example

- Create a 1d input signal: a discretized $sinc(x) = \sin(x)/x$ with 16384 points on the interval [-30:30].
- Perform forward transform
- Write to standard out
- Compile, and linking to fftw3 library.
- Continous FT of sinc(x) is the rectangle function:

$$\operatorname{rect}(f) = \left\{egin{array}{cc} 0.5 & ext{if} \; \|k\| \leq 1 \ 0 & ext{if} \; \|k\| > 1 \end{array}
ight.$$

up to a normalization.

Does it match?



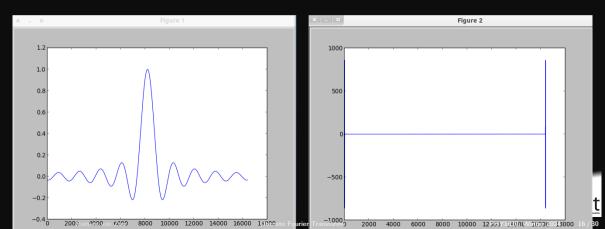
Code for the working example

```
#include <iostream>
#include <complex>
#include <rarrav>
#include <fftw3.h>
using complex = std::complex<double>;
int main() {
    const int n = 16384:
    rvector<complex> f(n), fhat(n);
    for (int i=0; i<n; i++) {</pre>
        double x = 60*(i/double(n)-0.5); // x-range from -30 to 30
        if (x!=0.0) f[i] = sin(x)/x; else f[i] = 1.0;
    fftw plan p = fftw plan dft 1d(n.
                       reinterpret_cast<fftw_complex*>(f.data()),
                       reinterpret cast<fftw complex*>(fhat.data()).
                       FFTW FORWARD, FFTW ESTIMATE):
    fftw_execute(p);
    fftw_destroy_plan(p);
    for (int i=0: i<n: i++)</pre>
        std::cout << f[i].real() << " " << fhat[i].real() << std::endl:</pre>
```



Compile, link, run, plot

\$ module load gcc/13 rarray fftw/3 python/3 \$ g++ -std=c++17 -c -03 sincfftw.cpp -o sincfftw.o \$ g++ sincfftw.o -o sincfftw -lfftw3 \$./sincfftw > output.dat \$ ipython --pylab >>> data = genfromtxt('output.dat')
>>> plot(data[:,0])
>>> figure()
>>> plot(data[:,1])

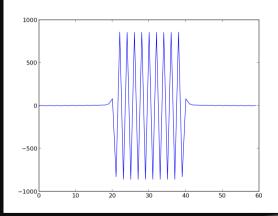


Plots of the output, rewrapped

Pick the first and the last 30 points.

>>> x1=range(30)
>>> x2=range(len(data)-30,len(data))
>>> y1=data[x1,1]
>>> y2=data[x2,1]
>>> figure()

>>> plot(hstack((y2,y1)))

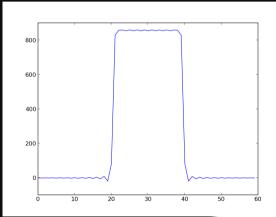




Undo phase factor due to shifting

>>> plot(hstack((y2,y1))*array([1,-1]*30)

We retrieved our rectangle function!





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Precise Relation FT and DFT

- Consider a function on f(x) an interval $[x_1,x_2].$
- The fourier analysis will express this in terms of periodic functions, so think of f as periodic.
- We will approximate this function with n discrete points on $x_1+j\Delta x$, where $\Delta x=(x_2-x_1)/n$, and j=0..n-1, i.e.

$$f(x) = \sum_{j=0}^{n-1} f_j \delta\left(x - (x_1 + j\Delta x)
ight) \Delta x$$

• Consider its continuous FT:

$$\hat{f}(k)=\int_{x_1}^{x_2}e^{ikx}f(x)\;dx$$

• e^{ikx} must have period (x_2-x_1) : $k=q imes 2\pi/(x_2-x_1)$ with q integer.



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Precise Relation FT and DFT

Input

$$f(x) = \sum_{j=0}^{n-1} f_j \deltaig(x - (x_1 + j\Delta x)ig)\Delta xig)$$

$$\Delta x = rac{x_2-x_1}{n}$$
 $\hat{f}(k) = \int_{x_1}^{x_2} e^{ikx} f(x) \; dx$

$$k=rac{2\pi}{x_2-x_1}q=rac{2\pi}{n\Delta x}q$$

Result

$$\hat{f}(k) = e^{ikx_1}\Delta x \ \hat{f}_q$$

$$\hat{f}(k)=\int_{x_1}^{x_2}\sum_{j=0}^{n-1}e^{ikx}f_j\deltaig(x{-}(x_1{+}j\Delta x)ig)\Delta x\;dx$$

$$=\sum_{j=0}^{n-1}f_je^{ik(x_1+j\Delta x)}\Delta x$$

$$=e^{ikx_1}\Delta x\sum_{j=0}^{n-1}f_je^{ikj\Delta x_j}$$

$$=e^{ikx_1}\Delta x\sum_{j=0}^{n-1}f_je^{2\pi iqj/n}$$



Multidimensional transforms

In principle a straighforward generalization:

• Given a set of n imes m function values on a regular grid:

$$f_{ab} = f(a\Delta x, b\Delta y)$$

• Transform these to n other values \widehat{f}_{kl}

$$\hat{f}_{kl} = \sum_{a=0}^{n-1} \sum_{b=0}^{m-1} f_{ab} \, e^{\pm \, 2\pi i \, (a \, k+b \; l)/n}$$

Easily back-transformed:

$$f_{ab} = rac{1}{nm} \sum_{k=0}^{n-1} \sum_{l=0}^{m-1} \hat{f}_{kl} \, e^{\mp \, 2\pi i \, (a \, k+b \; l)/n}$$

• Negative frequencies: $f_{-k,-l} = f_{n-k,m-l}$.

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Multidimensional FFT

- We could successive apply the FFT to each dimension
- This may require transposes, can be expensive.
- Alternatively, could apply FFT on rectangular patches.
- Mostly should let the libraries deal with this.
- FFT scaling still $n \log n$.



Symmetries for real data

- All arrays were complex so far.
- If input f is real, this can be exploited.

$$f_j^* = f_j \leftrightarrow \hat{f}_k = \hat{f}_{n-k}^*$$

- Each complex number holds two real numbers, but for the input f we only need n real numbers.
- If n is even, the transform \hat{f} has real \hat{f}_0 and $\hat{f}_{n/2}$, and the values of $\hat{f}_k > n/2$ can be derived from the complex valued $\hat{f}_{0 < k < n/2}$: again n real numbers need to be stored.



Symmetries for real data

- A different way of storing the result is in "half-complex storage". First, the n/2 real parts of $\hat{f}_{0 < k < n/2}$ are stored, then their imaginary parts in reversed order.
- Seems odd, but means that the magnitude of the wave-numbers is like that for a complex-to-complex transform.
- These kind of implementation dependent storage patterns can be tricky, especially in higher dimensions.



Applications?



Application of the Fourier transform

- Signal processing, certainly.
- Many equations become simpler in the fourier basis.
 - Reason: $\exp(ik \cdot x)$ are eigenfunctions of the $\partial/\partial x$ operator.
 - ► Partial diferential equation become algebraic ones, or ODEs.
 - Thus avoids matrix operations.
- Optimizing long range particle-particle interactions in N-body simulations and molecular dynamics.



Application: Solving diffusion equation with FFT

$$rac{\partial
ho}{\partial t} = \kappa rac{\partial^2
ho}{\partial x^2}$$

for ho(x,t) on $x\in[0,L]$, with boundary conditions ho(0,t)=
ho(L,t)=0, and ho(x,0)=f(x). Write

$$ho(x,t)=\sum_{k=-\infty}^\infty \hat
ho_k(t) e^{2\pi i k x/L}$$

then the PDE becomes an ODE:

$$rac{d\hat
ho_k}{dt}=-\kapparac{4\pi^2k^2}{L^2}\hat
ho_k;\qquad$$
 with $\hat
ho_k(0)=\hat f_k.$

Alternatively, one can first discretize the PDE, then take an FFT. This is numerically different.



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Application: Long-range particle interactions

- Long-range interactions are those that cannot be cut off without seriously altering the physics.
- Examples of a long range interactions include:
 - Gravity
 - Electrostatics
- In N-body and MD simulations, the force computation is often the bottleneck.
- Without a cut-off (as for short-range) interactions, we are left with a sum over interacting pairs, i.e., an or "Particle-Particle", $\mathcal{O}(N^2)$ method.

Enter P3M

Particle-Particle / Particle Mesh is (one) technique around this.

It uses the FFT.



Particle-Mesh

- Choose a fixed-size rectangular mesh
- Distribute masses (blue large circles) to mesh vertices (little black circles)
- Determine gravitational potential using FFT:

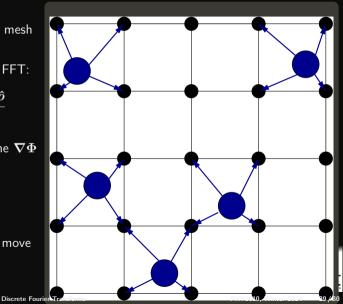
$$abla^2\Phi=4\pi G
ho\Rightarrow\hat{\Phi}=-rac{4\pi G\hat{
ho}}{k^2}$$

- The forces on the lattice are given by the $\boldsymbol{\nabla}\Phi$ in real space, i.e, the fourier inverse of

$$\hat{F}=i{
m k}\hat{\Phi}=-i{
m k}rac{4\pi G\hat{
ho}}{k^2}$$

- The inverse FFT gives the real force to move the particles with.
- $\mathcal{O}(N \log N)$.

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- Particle-Mesh is fast, but not very accurate.
- This is because the short range part of the forces is poorly represented.
- One can do better.
- Idea of P3M is to do an exact summation of forces with bodies nearby, and perform an approximate calculation for bodies further away.
- P3M still assigns masses to a regular grid, allowing for $\mathcal{O}(N\log N)$ scaling.
- It relies on being able to translate this separation of local and further-away in fourier space.
- Many choices possible, some better than others: quite outside the scope of this lecture, best stop.

